

## CONTROLLED $K$ -FRAMES IN 2-HILBERT SPACES

**Neha Pauriyal and Mahesh C. Joshi\***

Department of Applied Sciences and Humanities,  
Birla Institute of Applied Sciences,  
Bhimal - 263136, Uttarakhand, INDIA

E-mail : nehapauriyal1996@gmail.com

\*Department of Mathematics,  
D. S. B. Campus, Kumaun University,  
Nainital - 263002, Uttarakhand, INDIA

E-mail : mcjoshi69@gmail.com

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**Abstract:** In this paper, we introduce a new generalization of controlled  $K$ -frames to the context of 2-Hilbert spaces, thereby extending beyond classical Hilbert space theory. We develop foundational results by examining the operator-theoretic properties of controlled  $K$ -frames in this setting, establishing equivalent conditions that characterize them, and exploring their stability under suitable transformations. This builds directly on prior work introducing controlled  $K$ -frames in Hilbert  $C^*$ -modules, where the concept was first defined, equivalent conditions were established, relationships between  $K$ -frames and controlled  $K$ -frames were revealed, and invariance and perturbation properties were analyzed. Our work elevates these ideas by adapting them to the richer structure of 2-Hilbert spaces—a framework extending Hilbert spaces through inner products valued in  $C^*$ -algebras.

**Keywords and Phrases:** Frame, Controlled  $K$ -frame, Controlled  $K$ -frame operator, Controlled  $K$ - Bessel sequence.

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## 1. Introduction

Frames represent generalizations of the fundamental concept of bases within the study of vector spaces, initially formulated by Duffin and Schaeffer [5] during the 20th century in the context of non-harmonic Fourier series. This pioneering work laid the foundation for further exploration. Daubechies, Grossmann, and Meyer [3] continued to develop the idea, shedding light on frames. Today, frames play a crucial role not only in pure mathematics but also in applied mathematics, finding applications in signal and image processing [6], harmonic analysis [9], wireless communications [10], and various other fields.

Diminnie, Gahler, and White [4] introduced the concept of 2-inner product, paving the way for subsequent discussions. Building on this, Misiak [11] extended the notion of 2-inner product spaces to cases where  $n \geq 2$ .

Numerous generalizations have been proposed by researchers, such as  $K$ -frames [8],  $K$ - $d$ -frames [15, 16], approximative frames [17], approximative  $K$ -frames [13, 14], controlled frames [1], and more.

The concept of controlled frames was initially introduced by Balazs, Antoine, and Grybos [1] with the aim of enhancing the numerical efficiency of iterative algorithms used for inverting the frame operator. Subsequently, the idea of the controlled  $K$ -frame was developed by Nouri, Rahimi, and Najafzadeh [12]. Building on the foundation laid by the literature on frames, we introduce the novel concept of controlled  $K$ -frames within the context of two Hilbert spaces.

## 2. Preliminaries

Throughout this paper,  $\mathcal{H}$  denotes separable Hilbert space,  $\mathcal{B}(\mathcal{H})$  a collection of all bounded linear operators from  $\mathcal{H}$  to  $\mathcal{H}$  and  $\ell^2(\mathbb{N})$  denotes the square summable scalar valued sequences with index set of natural numbers  $\mathbb{N}$ .  $K^*$  is an adjoint of  $K$ . We denote  $GL(\mathcal{H}_1, \mathcal{H}_2)$  as the set of all bounded linear operators with a bounded inverse,  $GL(\mathcal{H})$  the set of all bounded linear operators with a bounded inverse from  $\mathcal{H}$  to  $\mathcal{H}$  and  $GL^+(\mathcal{H})$  be the set of positive operators in  $GL(\mathcal{H})$ .  $\mathbb{I}$  is the countable index set.

**Definition 1.** [2] *Let  $\mathcal{H}$  be a separable Hilbert space. A sequence  $\{x_i\}_{i \in \mathbb{I}}$  is called a frame for  $\mathcal{H}$ , if there exist constants  $b, B > 0$  such that*

$$b\|x\|^2 \leq \sum_{i \in \mathbb{I}} |\langle x, x_i \rangle|^2 \leq B\|x\|^2, \quad \forall x \in \mathcal{H},$$

here, constants  $b$  and  $B$  are called lower and upper frame bounds respectively. If  $\{x_i\}_{i \in \mathbb{I}}$  satisfies

$$\sum_{i \in \mathbb{I}} |\langle x, x_i \rangle|^2 \leq B\|x\|^2, \quad \forall x \in \mathcal{H},$$

then  $\{x_i\}_{i \in \mathbb{I}}$  is called a Bessel sequence with bound  $B$ .

**Definition 2.** [2] Let sequence  $\{x_i\}_{i \in \mathbb{I}}$  be a frame for  $\mathcal{H}$ . Then the bounded linear operator  $T : \mathcal{H} \rightarrow \ell^2(\mathbb{N})$ , defined by  $Tx = \{\langle x, x_i \rangle\}_{i \in \mathbb{I}}$  is called analysis operator and its adjoint operator  $T^* : \ell^2(\mathbb{N}) \rightarrow \mathcal{H}$ , defined by  $T^*(\{c_i\})_{i \in \mathbb{I}} = \sum_{i \in \mathbb{I}} c_i x_i$  is called synthesis or pre-frame operator. Then operator  $\mathcal{S} : \mathcal{H} \rightarrow \mathcal{H}$  defined by  $\mathcal{S}x = TT^*x = \sum_{i \in \mathbb{I}} \langle x, x_i \rangle x_i$  is called the frame operator.

**Definition 3.** [4] Let  $\mathcal{X}$  be a linear space of dimension greater than 1 over the field  $\mathbb{K}$  ( $\mathbb{K}$  is the real or complex numbers field). Let us consider  $\langle \cdot, \cdot | \cdot \rangle$  is a  $\mathbb{K}$ -valued function defined on  $\mathcal{X} \times \mathcal{X} \times \mathcal{X}$  satisfying the following conditions:-

- (i).  $\langle x, x | z \rangle \geq 0$  and  $\langle x, x | z \rangle = 0$  iff  $x$  and  $z$  are linearly dependent,
- (ii).  $\langle x, x | z \rangle = \langle z, z | x \rangle$ ,
- (iii).  $\langle y, x | z \rangle = \langle x, y | x \rangle$ ,
- (iv).  $\langle \alpha x, x | z \rangle = \alpha \langle x, y | z \rangle, \forall \alpha \in \mathbb{K}$ ,
- (v).  $\langle x_1 + x_2, y | z \rangle = \langle x_1, y | z \rangle + \langle x_2, y | z \rangle$ .

$\langle \cdot, \cdot | \cdot \rangle$  is called a 2-inner product on  $\mathcal{X}$  and  $(\mathcal{X}, \langle \cdot, \cdot | \cdot \rangle)$  is called 2-inner product space (or 2-pre Hilbert space). Some basic properties of 2-inner product  $\langle \cdot, \cdot | \cdot \rangle$  can be immediately obtained as follows ()

- (i).  $\langle 0, y | z \rangle = \langle x, 0 | z \rangle = \langle x, y | 0 \rangle = 0$ ,
- (ii).  $\langle x, \alpha y | z \rangle = \bar{\alpha} \langle x, y | z \rangle$ ,
- (iii).  $\langle x, y | \alpha z \rangle = |\alpha|^2 \langle x, y | z \rangle, \forall x, y, z \in \mathcal{X}$  and  $\alpha \in \mathbb{K}$ .

Using these properties, we can prove the Cauchy Schwarz inequality.

$$|\langle x, y | z \rangle|^2 \leq \langle x, x | z \rangle \langle y, y | z \rangle.$$

**Example 1.** If  $(\mathcal{X}, \langle \cdot, \cdot | \cdot \rangle)$  is an inner product space, then the standard 2-inner product  $\langle \cdot, \cdot | \cdot \rangle$  is defined on  $\mathcal{X}$  by

$$\langle x, y | z \rangle = \begin{vmatrix} \langle x, y \rangle & \langle x, z \rangle \\ \langle z, y \rangle & \langle z, z \rangle \end{vmatrix} = \langle x, y \rangle \langle z, z \rangle - \langle x, z \rangle \langle z, y \rangle, \forall x, y, z \in \mathcal{X}.$$

In any given 2-inner product space  $(\mathcal{X}, \langle \cdot, \cdot | \cdot \rangle)$ , we can define a function  $\|\cdot, \cdot\|$  defined on  $\mathcal{X} \times \mathcal{X}$  by

$$\|x, z\| = \langle x, x | z \rangle^{1/2}, \forall x, y, z \in \mathcal{X}.$$

**Definition 4.** [7] Any function  $\|\cdot, \cdot\|$  defined on  $\mathcal{X} \times \mathcal{X}$  and satisfying the following conditions is called 2-norm on  $\mathcal{X}$  and  $(\mathcal{X}, \|\cdot, \cdot\|)$  is called 2-normed space.

- (i).  $\|x, z\| \geq 0$  and  $\|x, z\| = 0$  if and only if  $x$  and  $z$  are linearly dependent,
- (ii).  $\|x, z\| = \|z, x\|$ ,

(iii).  $\|\alpha x, z\| = |\alpha| \|x, z\|, \forall \alpha \in \mathbb{K},$  (iv).  $\|x_1 + x_2, z\| = \|x_1 + z\| + \|x_2 + z\|$

**Definition 5.** [12] Let  $C \in GL^+(\mathcal{H})(C > 0), K \in \mathcal{B}(\mathcal{H})$  and  $CK = KC$ . A family  $\{x_i\}_{i \in \mathbb{I}} \in \mathcal{H}$  is a controlled  $K$ -frames if there exist  $b > 0, B < \infty$  such that

$$b \|C^{1/2} K^* x\|^2 \leq \sum_{i \in \mathbb{I}} \langle x, x_i \rangle \langle C x_i, x \rangle \leq B \|x\|^2, \quad \forall x \in \mathcal{H}, \quad (1)$$

where  $b$  and  $B$  are lower and upper bounds of controlled  $K$ -frames for  $\mathcal{H}$ .

**Remark 1.** (i). If  $C = I, \{x_i\}_{i \in \mathbb{I}}$  is called  $K$ -frame for  $\mathcal{H}$  with bounds  $b$  and  $B$ . (ii). If  $\sum_{i \in \mathbb{I}} \langle x, x_i \rangle \langle C x_i, x \rangle \leq B \|x\|^2$ , then  $\{x_i\}_{i \in \mathbb{I}}$  is called controlled  $K$ -Bessel sequence for  $\mathcal{H}$  with bound  $B$ .

### 3. Controlled $K$ -Frame in 2-Hilbert Space

In this section, we introduce the notion of controlled  $K$ -frame in 2 Hilbert space. For the rest of the part, we assume  $\langle \mathcal{X}, \cdot | \cdot \rangle$  is 2- Hilbert space and  $L_\rho$  the subspace generated with  $\rho$  for a fix element  $\rho$  in  $\mathcal{X}$ .  $M_\rho$  be the algebraic complement of  $L_\rho$  in  $\mathcal{X}$ . So  $L_\rho \oplus M_\rho = \mathcal{X}$ .

Define  $\langle x, y \rangle_\rho$  on  $\mathcal{X}$  as following:

$$\langle x, y \rangle_\rho = \langle x, y | \rho \rangle.$$

The semi-inner product induces an inner product on the quotient space  $\mathcal{X} | L_\rho$  as

$$\langle x + L_\rho, y + L_\rho \rangle_\rho = \langle x, y \rangle_\rho = \langle x, y | \rho \rangle, \forall x, y \in \mathcal{X}.$$

By introducing  $\mathcal{X} | L_\rho$  with  $M_\rho$  is an obvious way, we obtain an inner product on  $M_\rho$ . Define  $\|x\|_\rho = \sqrt{\langle x, x \rangle_\rho} = \sqrt{\langle x, x | \rho \rangle}, x \in M_\rho$ . Then  $(M_\rho, \|\cdot\|_\rho)$  is a norm space. Let  $\mathcal{X}_\rho$  be the completion of the inner product space  $M_\rho$ .

**Definition 6.** Let  $C \in GL^+(\mathcal{X}_\rho)(C > 0), K \in \mathcal{B}(\mathcal{X}_\rho)$  and  $CK = KC$ . Let  $(\mathcal{X}, \langle \cdot, \cdot | \cdot \rangle)$  be a Hilbert space and  $\rho \in \mathcal{X}$ . A family  $\{x_i\}_{i \in \mathbb{I}} \in \mathcal{X}$  is a controlled  $K$ -frames associated to  $\rho$  if there exist  $b > 0, B < \infty$  such that

$$b \|C^{1/2} K^* x, \rho\|^2 \leq \sum_{i \in \mathbb{I}} \langle x, x_i | \rho \rangle \langle C x_i, x | \rho \rangle \leq B \|x, \rho\|^2, \quad \forall x \in \mathcal{X}_\rho, \quad (2)$$

where  $b$  and  $B$  are lower and upper bounds of controlled  $K$ -frames associated to  $\rho$  for  $\mathcal{X}$ .

**Remark 2.** If  $C = I, \{x_i\}_{i \in \mathbb{I}}$  is called  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$  with bounds  $b$  and  $B$ .

**Remark 3.** If  $\sum_{i \in \mathbb{I}} \langle x, x_i | \rho \rangle \langle Cx_i, x | \rho \rangle \leq B \|x, \rho\|^2$ , then  $\{x_i\}_{i \in \mathbb{I}}$  is called controlled  $K$ -Bessel sequence associated to  $\rho$  for  $\mathcal{X}$  with bound  $B$ .

**Remark 4.** If  $b \|C^{1/2} K^* x, \rho\|^2 = \sum_{i \in \mathbb{I}} \langle x, x_i | \rho \rangle \langle Cx_i, x | \rho \rangle$  in equation (2) then  $\{x_i\}_{i \in \mathbb{I}}$  is called controlled  $K$ -tight frame associated to  $\rho$  for  $\mathcal{X}$  with bound  $b$ .

**Remark 5.** Let  $\{x_i\}_{i \in \mathbb{I}}$  is called controlled  $K$ -tight frame associated to  $\rho$  for  $\mathcal{X}$  with bound  $b$ . Then  $\forall x \in \mathcal{X}_\rho$ , we have

$$\begin{aligned} & \sum_{i \in \mathbb{I}} \langle x, x_i | \rho \rangle \langle Cx_i, x | \rho \rangle = b \|K^* C^{1/2} x, \rho\|^2 \\ \implies & \frac{1}{b} \sum_{i \in \mathbb{I}} \langle x, x_i | \rho \rangle \langle Cx_i, x | \rho \rangle = \|K^* C^{1/2} x, \rho\|^2 \\ \implies & b^{-1} \sum_{i \in \mathbb{I}} \langle x, x_i | \rho \rangle \langle Cx_i, x | \rho \rangle = \|K^* C^{1/2} x, \rho\|^2 \\ \implies & \sum_{i \in \mathbb{I}} \langle x, b^{-1/2} x_i | \rho \rangle \langle Cb^{-1/2} x_i, x | \rho \rangle = \|K^* C^{1/2} x, \rho\|^2. \end{aligned}$$

$\implies \{b^{-1/2} x_i\}_{i \in \mathbb{I}}$  is a controlled  $K$ -Parseval frame associated to  $\rho$  for  $\mathcal{X}$ .

#### 4. Controlled $K$ -Frame Operators for 2-Hilbert Space

Let  $\{x_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -Bessel sequence associated to  $\rho$  for  $\mathcal{X}$ . The operator  $T_{\mathcal{X}_\rho} : \mathcal{X}_\rho \rightarrow \ell^2(\mathbb{N})$  defined by,

$$T_{\mathcal{X}_\rho} x = \{\langle x, x_i | \rho \rangle\}_{i \in \mathbb{I}}, x \in \mathcal{X}_\rho.$$

$T_{\mathcal{X}_\rho}$  is called analysis operator.

Synthesis or pre-controlled  $K$ -frame operator  $T_{\mathcal{X}_\rho}^* : \ell^2(\mathbb{N}) \rightarrow \mathcal{X}_\rho$

$$T_{\mathcal{X}_\rho}^* (\{a_i\}_{i \in \mathbb{I}}) = \sum_{i \in \mathbb{I}} a_i Cx_i.$$

The controlled  $K$ -frame operator  $\mathcal{S}_{\mathcal{X}_\rho} : \mathcal{X}_\rho \rightarrow \mathcal{X}_\rho$

$$\mathcal{S}_{\mathcal{X}_\rho} x = T_{\mathcal{X}_\rho}^* T_{\mathcal{X}_\rho} x = \sum_{i \in \mathbb{I}} \langle x, x_i | \rho \rangle Cx_i.$$

**Proposition 1.** Let  $C \in GL^+(\mathcal{X}_\rho)$  ( $C > 0$ ),  $K \in \mathcal{B}(\mathcal{X}_\rho)$  and let  $\{x_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$  with bounds  $b$  and  $B$ . Then,  $\mathcal{S}_{\mathcal{X}_\rho}$  is bounded.

**Proof.** Let  $\{x_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$  with bounds  $b$  and  $B$ . So,  $\forall x \in \mathcal{X}_\rho$

$$\begin{aligned} b\langle C^{1/2}K^*x, C^{1/2}K^*x|\rho \rangle &\leq \sum_{i \in \mathbb{I}} \langle x, x_i|\rho \rangle \langle Cx_i, x|\rho \rangle \leq B\langle x, x|\rho \rangle \\ bC\|K^*x, \rho\|^2 &\leq \mathcal{S}_{\mathcal{X}_\rho} \leq B\|x, \rho\|^2 \\ bCKK^*I &\leq \mathcal{S}_{\mathcal{X}_\rho} \leq BI. \end{aligned}$$

**Corollary 1.** Let  $C \in GL^+(\mathcal{X}_\rho)$  ( $C > 0$ ),  $K \in \mathcal{B}(\mathcal{X}_\rho)$  and let  $\{x_i\}_{i \in \mathbb{I}}$  be a controlled Bessel sequence associated to  $\rho$  in  $\mathcal{X}$ . Then  $\{x_i\}_{i \in \mathbb{I}}$  is a controlled  $K$ -frame associated to  $\rho$  in  $\mathcal{X}$  if and only if there exists  $b > 0$  such that

$$CS \geq bCKK^*.$$

**Proof.** Let  $\{x_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -frame associated to  $\rho$  in  $\mathcal{X}$  with bounds  $b$  and  $B$ . Then,  $\forall x \in \mathcal{X}_\rho$

$$\begin{aligned} b\langle C^{1/2}K^*x, C^{1/2}K^*x|\rho \rangle &\leq \sum_{i \in \mathbb{I}} \langle x, x_i|\rho \rangle \langle Cx_i, x|\rho \rangle \leq B\langle x, x|\rho \rangle \\ \iff b\langle CKK^*x, x|\rho \rangle &\leq \langle \mathcal{S}_{\mathcal{X}_\rho}x, x|\rho \rangle \leq B\langle x, x|\rho \rangle \\ \iff b\langle CKK^*x, x|\rho \rangle &\leq \langle C\mathcal{S}x, x|\rho \rangle \leq B\langle x, x|\rho \rangle \\ \iff bCKK^*I &\leq C\mathcal{S} \leq BI \\ \iff bCKK^*I &\leq C\mathcal{S}. \end{aligned}$$

**Theorem 2.** Let  $\{x_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$  and  $\mathcal{S}_{\mathcal{X}_\rho}$  be 2-controlled  $K$ -frame operator of  $\{x_i\}_{i \in \mathbb{I}}$  where  $KK^* = I$ . If we denote the positive square root of  $\mathcal{S}_{\mathcal{X}_\rho}^{-1}x_i$  by  $\mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x_i$  then the  $\{\mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x_i\}_{i \in \mathbb{I}}$  is a Parseval controlled  $K$ -frame associated to  $\rho$ .

**Proof.** 2-Controlled  $K$ -frame operator

$$\mathcal{S}_{\mathcal{X}_\rho}x = \sum_{i \in \mathbb{I}} \langle x, x_i|\rho \rangle Cx_i$$

Putting  $x = \mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x$

$$\begin{aligned} \mathcal{S}_{\mathcal{X}_\rho}^{1/2}x &= \sum_{i \in \mathbb{I}} \langle \mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x, x_i|\rho \rangle Cx_i \\ x &= \mathcal{S}_{\mathcal{X}_\rho}^{-1/2} \left( \sum_{i \in \mathbb{I}} \langle x, \mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x_i|\rho \rangle Cx_i \right) \\ &= \sum_{i \in \mathbb{I}} \langle x, \mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x_i|\rho \rangle \mathcal{S}_{\mathcal{X}_\rho}^{-1/2} Cx_i \end{aligned}$$

Now,

$$\begin{aligned}
\|C^{1/2}K^*x, \rho\|^2 &= \langle C^{1/2}K^*x, C^{1/2}K^*x|\rho \rangle \\
&= \langle C^{1/2}K^* \sum_{i \in \mathbb{I}} \langle x, \mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x_i|\rho \rangle \mathcal{S}_{\mathcal{X}_\rho}^{-1/2}Cx_i, C^{1/2}K^*x|\rho \rangle \\
&= \sum_{i \in \mathbb{I}} \langle x, \mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x_i|\rho \rangle \langle C^{1/2}K^*\mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x_i, C^{1/2}K^*x|\rho \rangle \\
&= \sum_{i \in \mathbb{I}} \langle x, \mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x_i|\rho \rangle \langle C\mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x_i, x|\rho \rangle
\end{aligned}$$

Hence  $\{\mathcal{S}_{\mathcal{X}_\rho}^{-1/2}x_i\}_{i \in \mathbb{I}}$  is a Parseval 2-controlled  $K$ -frame for  $\mathcal{X}$ .

**Proposition 3.** Let  $\{x_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -Bessel sequence associated to  $\rho$  for  $\mathcal{X}$  with bound  $B$ . Let  $M \in \mathcal{B}(\mathcal{X}_\rho)$  and  $CM = MC$ . Then,  $\{Mx_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -Bessel sequence associated to  $\rho$  for  $\mathcal{X}$  with bound  $B\|M^*, \rho\|^2$ .

**Proof.** Let  $\{x_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -Bessel sequence associated to  $\rho$ . Then,  $\forall x \in \mathcal{X}_\rho$

$$\begin{aligned}
\sum_{i \in \mathbb{I}} \langle x, x_i|\rho \rangle \langle Cx_i, x|\rho \rangle &\leq B\langle x, x|\rho \rangle \\
\sum_{i \in \mathbb{I}} \langle x, Mx_i|\rho \rangle \langle CMx_i, x|\rho \rangle &= \sum_{i \in \mathbb{I}} \langle M^*x, x_i|\rho \rangle \langle MCx_i, x|\rho \rangle \\
&\leq B\langle M^*x, M^*x|\rho \rangle \\
&\leq B\|M^*, \rho\|^2 \langle x, x|\rho \rangle.
\end{aligned}$$

Hence,  $\{Mx_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -Bessel sequence associated to  $\rho$  for  $\mathcal{X}$  with bound  $B\|M^*, \rho\|^2$ .

**Theorem 4.** Let  $K \in \mathcal{B}(\mathcal{X}_\rho)$  and let  $\{x_i\}_{i \in \mathbb{I}}$  be a 2-controlled  $K$ -frame for  $\mathcal{X}_\rho$ . If  $M \in \mathcal{B}(\mathcal{X}_\rho)$  has closed range with  $R(K^*) \subset R(M)$ ,  $MK = KM$  and  $MC = CM$ , then  $\{Mx_i\}_{i \in \mathbb{I}}$  is a 2-controlled  $K$ -frame for  $R(M)$ .

**Proof.** We know that  $M$  has pseudo-inverse  $M^\dagger$  since it has closed range such that

$$MM^\dagger = I_{R(M)}.$$

Now  $I_{R(M)} = I_{R(M)}^* = (M^\dagger)^*M^*$ . Since  $R(K^*) \subset R(M)$  then for each  $x \in R(M)$ ,

$$\begin{aligned}
K^*x &= (M^\dagger)^*M^*K^*x \\
\|K^*x, \rho\| &= \|(M^\dagger)^*M^*K^*x, \rho\| \leq \|(M^\dagger)^*\| \|M^*K^*x, \rho\|
\end{aligned}$$

It implies,  $\|(M^\dagger)^*\|^{-1}\|K^*x, \rho\| \leq \|M^*K^*x, \rho\|$ .

Now for each  $x \in R(M)$ ,

$$\begin{aligned} b\|(M^\dagger)^*\|^{-2}\|K^*x, \rho\|^2 &= b\|M^*K^*x, \rho\|^2 \\ &\leq \sum_{i \in \mathbb{I}} \langle M^*x, x_i | \rho \rangle \langle Cx_i, M^*x | \rho \rangle \\ &= \sum_{i \in \mathbb{I}} \langle x, Mx_i | \rho \rangle \langle MCx_i, x | \rho \rangle \\ &= \sum_{i \in \mathbb{I}} \langle x, Mx_i | \rho \rangle \langle CMx_i, x | \rho \rangle \\ &\leq B\|M\|^2\|x, \rho\|^2. \end{aligned}$$

The following result shows that a controlled  $K$ -frame associated to  $\rho$  is a  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$ .

**Theorem 5.** Let  $\{x_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$  and  $C \in GL^+(\mathcal{X}_\rho)$ . Then,  $\{x_i\}_{i \in \mathbb{I}}$  is a  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$ .

**Proof.** Let  $\{x_i\}_{i \in \mathbb{I}}$  be a controlled  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$  with bounds  $A$  and  $B$ . Then,  $\forall x \in \mathcal{X}_\rho$

$$\begin{aligned} b\|K^*x, \rho\|^2 &= b\|C^{-1/2}C^{1/2}K^*x, \rho\|^2 \\ &\leq b\|C^{1/2}\|^2\|C^{-1/2}K^*x, \rho\|^2 \\ &\leq \|C^{1/2}\|^2 \sum_{i \in \mathbb{I}} \langle x, x_i | \rho \rangle \langle C^0x_i, x | \rho \rangle \\ &= \|C^{1/2}\|^2 \sum_{i \in \mathbb{I}} |\langle x, x_i | \rho \rangle|^2. \end{aligned}$$

Hence,

$$b\|C^{1/2}\|^{-2}\|K^*x, \rho\|^2 \leq \sum_{i \in \mathbb{I}} |\langle x, x_i | \rho \rangle|^2.$$

For the upper bound,

$$\begin{aligned} \sum_{i \in \mathbb{I}} |\langle x, x_i | \rho \rangle|^2 &= \langle x, \mathcal{S}x | \rho \rangle = \langle x, C^{-1}C\mathcal{S}x | \rho \rangle \\ &= \langle (C^{-1}C\mathcal{S})^{1/2}x, (C^{-1}C\mathcal{S})^{1/2}x | \rho \rangle \\ &= \|(C^{-1}C\mathcal{S})^{1/2}x, \rho\|^2 \\ &\leq \|C^{-1/2}\|^2\|(C\mathcal{S})^{1/2}x, \rho\|^2 \\ &= \|C^{-1/2}\|^2\langle x, C\mathcal{S}x | \rho \rangle \\ &\leq \|C^{-1/2}\|^2B\|x, \rho\|^2. \end{aligned}$$

So,  $\{x_i\}_{i \in \mathbb{I}}$  is a  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$ . with bounds  $b\|C^{1/2}\|^{-2}$  and  $B\|C^{-1/2}\|^2$ .

We discuss the following condition when a  $K$ -frame associated to  $\rho$  is a controlled  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$ .

**Theorem 6.** *Let  $C \in GL^+(\mathcal{X}_\rho)$  be a self-adjoint and  $KC = CK$ , if  $\{x_i\}_{i \in \mathbb{I}}$  is a  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$  with bounds  $b$  and  $B$ , then  $\{x_i\}_{i \in \mathbb{I}}$  is a controlled  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$  with bounds  $b$  and  $B\|C\|$ .*

**Proof.** Let  $\{x_i\}_{i \in \mathbb{I}}$  be a  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$ . Then,  $\forall x \in \mathcal{X}_\rho$

$$\begin{aligned} b\|K^*x, \rho\|^2 &\leq \sum_{i \in \mathbb{I}} |\langle x, x_i | \rho \rangle|^2 \leq B\|x\|^2. \\ b\|C^{1/2}K^*x, \rho\|^2 = b\|K^*C^{1/2}x, \rho\|^2 &\leq \sum_{i \in \mathbb{I}} \langle C^{1/2}x, x_i | \rho \rangle \langle C^{1/2}x, x_i | \rho \rangle \\ &= \langle C^{1/2}x, \sum_{i \in \mathbb{I}} \langle x_i | \rho, C^{1/2}x \rangle x_i | \rho \rangle \\ &= \langle C^{1/2}x, C^{1/2}\mathcal{S}x | \rho \rangle = \langle x, C\mathcal{S}x | \rho \rangle. \end{aligned}$$

On the other hand,  $\forall x \in \mathcal{X}_\rho$

$$\begin{aligned} |\langle x, C\mathcal{S}x | \rho \rangle|^2 &= |\langle C^*x, \mathcal{S}x | \rho \rangle|^2 = |\langle Cx, \mathcal{S}x | \rho \rangle|^2 \\ &\leq \|Cx, \rho\|^2 \|\mathcal{S}x, \rho\|^2 \leq \|C\|^2 \|x, \rho\|^2 B\|x, \rho\|^2. \end{aligned}$$

Thus,

$$b\|C^{1/2}K^*x, \rho\|^2 \leq \langle x, C\mathcal{S}x | \rho \rangle \leq B\|C\| \|x, \rho\|^2.$$

Hence,  $\{x_i\}_{i \in \mathbb{I}}$  is a controlled  $K$ -frame associated to  $\rho$  for  $\mathcal{X}$  with bounds  $b$  and  $B\|C\|$ .

## 5. Conclusion

This paper broadens the concept of controlled  $K$ -frames to the setting of 2-Hilbert spaces, providing a comprehensive analysis of their properties and associated operators. We reinforce the structural foundation of these frames in this extended framework. Furthermore, the conditions under which a  $K$ -frame in a 2-Hilbert space can also serve as a controlled  $K$ -frame are rigorously examined, contributing to a deeper understanding of the interplay between these two notions in the context of 2-Hilbert spaces. These advancements have potential applications in various fields, including cryptography and secure communication, seismic signal processing, and other domains requiring robust and flexible signal representations.

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